

# C.U.SHAH UNIVERSITY

## Winter Examination-2015

Subject Name: Electrical Machine - III

Subject Code: 4TE05EMC1

Branch: B.Tech (Electrical)

Semester: 5      Date: 09/12/2015      Time: 2.30 To 5.30      Marks: 70

Instructions:

- (1) Use of Programmable calculator & any other electronic instrument is prohibited.
  - (2) Instructions written on main answer book are strictly to be obeyed.
  - (3) Draw neat diagrams and figures (if necessary) at right places.
  - (4) Assume suitable data if needed.
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Q-1

Attempt the following questions:

(14)

- a) Why do hybrid stepping motors have many phases sometime more than six?
- b) The rotor of a stepper motor has
  - (i) no windings
  - (ii) no commutator
  - (iii) no brushes
  - (iv) all of the above
- c) The electric motor used in domestic mixers is
  - (i) universal motor
  - (ii) shaded pole motor
  - (iii) capacitor start motor
  - (iv) hysteresis motor
- d) Synchronous capacitor is
  - (i) An ordinary static capacitor bank
  - (ii) An over excited synchronous motor running without mechanical load
  - (iii) An over excited synchronous motor driving mechanical load
  - (iv) None of the above
- e) The maximum value of torque angle  $\alpha$  in a synchronous motor is ..... degrees electrical.
  - (i) 45
  - (ii) 90
  - (iii) between 45 and 90
  - (iv) below 60
- f) The main thing common between Hopkinson's test and Field's test is that both
  - (i) requires two electrically-coupled series motors
  - (ii) need two similar mechanically-coupled motors
  - (iii) use negligible power
  - (iv) are regenerative tests
- g) At leading p.f. the armatures flux in an alternator \_\_\_\_\_ the rotor flux.
  - (i) opposes
  - (ii) distorts
  - (iii) aids
  - (iv) does not affect
- h) When load on a synchronous motor is increased its armature current is increased provided it is
  - (i) normally excited
  - (ii) over excited
  - (iii) under excited
  - (iv) all of the above



- i) Which alternator are more suitable for high-speed system?  
 (i) salient pole (ii) non – salient pole  
 (iii) both (i) and (ii) (iv) none of these
- j) Define: Hunting.
- k) An unexcited single phase synchronous motor is  
 (i) AC series motor (ii) universal motor  
 (iii) reluctance motor (iv) repulsion motor
- l) In synchronous motor inverted V curve represents the relation between  
 (i) field current and power factor (ii) field current and armature current  
 (iii) armature current and power factor (iv) none of these
- m) One of the basic requirements of a servomotor is that it must produce high torque at all  
 (i) loads (ii) frequencies  
 (iii) speeds (iv) voltages
- n) A switched reluctance motor differs from a VR stepper motor in the sense that it  
 (i) has rotor poles of ferromagnetic material  
 (ii) rotates continuously  
 (iii) is designed for open-loop operation only  
 (iv) has lower efficiency

**Attempt any four questions from Q-2 to Q-8**

- Q-2 Attempt all questions (14)**  
 (a) Explain Hopkinson's test for determination of efficiency of DC shunt machine.  
 (b) Explain Armature reaction and its effects at different power factor in Alternator.
- Q-3 Attempt all questions (14)**  
 (a) Explain the operation of A.C. servo motor.  
 (b) What are the different types of torques in synchronous motor? Explain each of them.
- Q-4 Attempt all questions (14)**  
 (a) Explain the slip test for measurement of  $X_d$  and  $X_q$  of synchronous machines.  
 (b) A 3300 V, delta – connected motor has a synchronous motor has a synchronous reactance per phase (delta) of  $18\Omega$ . It operates at a leading power factor of 0.707 when drawing 800 kW from the mains. Calculate its excitation emf.
- Q-5 Attempt all questions (14)**  
 (a) Explain construction and working of variable reluctance stepper motor.  
 (b) Describe the experimental setup to obtain the V-curves of a synchronous motor.
- Q-6 Attempt all questions (14)**  
 (a) Explain single phase synchronous generator.  
 (b) A 400 V, 50 Hz, 3-phase, 37.5 KW, star connected synchronous motor has a full-load efficiency of 88%. The synchronous impedance of the motor is  $(0.2+j1.6)$  ohm per phase. If the excitation of the motor is adjusted to give a leading pf of 0.9, Calculate for full-load (a) the induced emf (b) total mechanical power



